

ABSTRACT OF THE DISCLOSURE

A general purpose hand for a multiaxis manipulator which includes a suction holder. The suction holder includes: a
5 suction pad to be sucked onto the handled object; an axially movable rod member supporting the suction pad as rotatable; a resilient member for pressing the suction pad toward the handled object; a first locking mechanism for locking axial movement of the rod member; and a second locking mechanism
10 for locking rotation of the suction pad. The suction holder is slidably mounted on the frame member carried by the multiaxis manipulator.